

# Package ‘kimfilter’

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**Type** Package

**Title** Kim Filter

**Version** 1.0.1

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**Description** 'Rcpp' implementation of the multivariate Kim filter, which combines the Kalman and Hamilton filters for state probability inference. The filter is designed for state space models and can handle missing values and exogenous data in the observation and state equations. Kim, Chang-Jin and Charles R. Nelson (1999) "State-Space Models with Regime Switching: Classical and Gibbs-Sampling Approaches with Applications" <<http://econ.korea.ac.kr/~cjkim/doi:10.7551/mitpress/6444.001.0001>><<http://econ.korea.ac.kr/~cjkim/>>.

**License** GPL (>= 2)

**Imports** Rcpp (>= 1.0.9)

**LinkingTo** Rcpp, RcppArmadillo

**RoxygenNote** 7.2.1

**Suggests** data.table (>= 1.14.2), maxLik (>= 1.5-2), ggplot2 (>= 3.3.6), gridExtra (>= 2.3), knitr, rmarkdown, testthat

**VignetteBuilder** knitr

**Encoding** UTF-8

**NeedsCompilation** yes

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**Depends** R (>= 3.5.0)

**Repository** CRAN

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contains	<i>Check if list contains a name</i>
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**Description**

Check if list contains a name

**Usage**

```
contains(s, L)
```

**Arguments**

s	a string name
L	a list object

**Value**

boolean

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gen_inv	<i>Generalized matrix inverse</i>
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**Description**

Generalized matrix inverse

**Usage**

```
gen_inv(m)
```

**Arguments**

m	matrix
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**Value**

matrix inverse of m

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kimfilter

*Kim Filter*

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**Description**

*kimfilter* Rcpp implementation of the multivariate Kim filter, which combines the Kalman and Hamilton filters for state probability inference. The filter is designed for state space models and can handle missing values and exogenous data in the observation and state equations. `browseVignettes("kimfilter")` to view it in your browser.

**Author(s)**

Alex Hubbard

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kim\_filter

*Kim Filter*

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**Description**

Kim Filter

**Usage**

```
kim_filter(ssm, yt, Xo = NULL, Xs = NULL, weight = NULL, smooth = FALSE)
```

**Arguments**

ssm	list describing the state space model, must include names B0 - $N_b \times 1$ matrix, initial guess for the unobserved components P0 - $N_b \times N_b$ matrix, initial guess for the covariance matrix of the unobserved components Dm - $N_b \times 1$ matrix, constant matrix for the state equation Am - $N_y \times 1$ matrix, constant matrix for the observation equation Fm - $N_b \times p$ matrix, state transition matrix Hm - $N_y \times N_b$ matrix, observation matrix Qm - $N_b \times N_b$ matrix, state error covariance matrix Rm - $N_y \times N_y$ matrix, state error covariance matrix betaO - $N_y \times N_o$ matrix, coefficient matrix for the observation exogenous data betaS - $N_b \times N_s$ matrix, coefficient matrix for the state exogenous data Pm - $n_{state} \times n_{state}$ matrix, state transition probability matrix
yt	$N \times T$ matrix of data
Xo	$N_o \times T$ matrix of exogenous observation data
Xs	$N_s \times T$ matrix of exogenous state
weight	column matrix of weights, $T \times 1$
smooth	boolean indication whether to run the backwards smoother

**Value**

list of cubes and matrices output by the Kim filter

**Examples**

```
#Stock and Watson Markov switching dynamic common factor
library(kimfilter)
library(data.table)
data(sw_dcf)
data = sw_dcf[, colnames(sw_dcf) != "dcoinc", with = FALSE]
vars = colnames(data)[colnames(data) != "date"]

#Set up the state space model
ssm = list()
ssm[["Fm"]] = rbind(c(0.8760, -0.2171, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 1, 0, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0.0364, -0.0008, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, -0.2965, -0.0657, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, -0.3959, -0.1903, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -0.2436, 0.1281),
                   c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 1, 0))
ssm[["Fm"]] = array(ssm[["Fm"]], dim = c(dim(ssm[["Fm"]]), 2))
ssm[["Dm"]] = matrix(c(-1.5700, rep(0, 11)), nrow = nrow(ssm[["Fm"]]), ncol = 1)
ssm[["Dm"]] = array(ssm[["Dm"]], dim = c(dim(ssm[["Dm"]]), 2))
ssm[["Dm"]][1, 2] = 0.2802
ssm[["Qm"]] = diag(c(1, 0, 0, 0, 0.0001, 0, 0.0001, 0, 0.0001, 0, 0.0001, 0))
ssm[["Qm"]] = array(ssm[["Qm"]], dim = c(dim(ssm[["Qm"]]), 2))
ssm[["Hm"]] = rbind(c(0.0058, -0.0033, 0, 0, 1, 0, 0, 0, 0, 0, 0, 0),
                   c(0.0011, 0, 0, 0, 0, 0, 1, 0, 0, 0, 0, 0),
                   c(0.0051, -0.0033, 0, 0, 0, 0, 0, 0, 1, 0, 0, 0),
                   c(0.0012, -0.0005, 0.0001, 0.0002, 0, 0, 0, 0, 0, 0, 1, 0))
ssm[["Hm"]] = array(ssm[["Hm"]], dim = c(dim(ssm[["Hm"]]), 2))
ssm[["Am"]] = matrix(0, nrow = nrow(ssm[["Hm"]]), ncol = 1)
ssm[["Am"]] = array(ssm[["Am"]], dim = c(dim(ssm[["Am"]]), 2))
ssm[["Rm"]] = matrix(0, nrow = nrow(ssm[["Am"]]), ncol = nrow(ssm[["Am"]]))
ssm[["Rm"]] = array(ssm[["Rm"]], dim = c(dim(ssm[["Rm"]]), 2))
ssm[["B0"]] = matrix(c(rep(-4.60278, 4), 0, 0, 0, 0, 0, 0, 0))
ssm[["B0"]] = array(ssm[["B0"]], dim = c(dim(ssm[["B0"]]), 2))
ssm[["B0"]][1:4, 2] = rep(0.82146, 4)
ssm[["P0"]] = rbind(c(2.1775, 1.5672, 0.9002, 0.4483, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(1.5672, 2.1775, 1.5672, 0.9002, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0.9002, 1.5672, 2.1775, 1.5672, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0.4483, 0.9002, 1.5672, 2.1775, 0, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0.0001, 0, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0.0001, 0, 0, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, 0.0001, -0.0001, 0, 0, 0, 0),
                   c(0, 0, 0, 0, 0, 0, -0.0001, 0.0001, 0, 0, 0, 0),
```

```

c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0.0001, -0.0001, 0, 0),
c(0, 0, 0, 0, 0, 0, 0, 0, 0, -0.0001, 0.0001, 0, 0),
c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0.0001, -0.0001),
c(0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, -0.0001, 0.0001))
ssm[["P0"]] = array(ssm[["P0"]], dim = c(dim(ssm[["P0"]]), 2))
ssm[["Pm"]] = rbind(c(0.8406, 0.0304),
                    c(0.1594, 0.9696))

#Log, difference and standardize the data
data[, c(vars) := lapply(.SD, log), .SDcols = c(vars)]
data[, c(vars) := lapply(.SD, function(x){
  x - shift(x, type = "lag", n = 1)
}), .SDcols = c(vars)]
data[, c(vars) := lapply(.SD, scale), .SDcols = c(vars)]

#Convert the data to an NxT matrix
yt = t(data[, c(vars), with = FALSE])
kf = kim_filter(ssm, yt, smooth = TRUE)

```

Rginv

*R's implementation of the Moore-Penrose pseudo matrix inverse***Description**

R's implementation of the Moore-Penrose pseudo matrix inverse

**Usage**

Rginv(m)

**Arguments**

m                   matrix

**Value**

matrix inverse of m

self\_rbind

*Matrix self rowbind***Description**

Matrix self rowbind

**Usage**

self\_rbind(mat, times)

**Arguments**

mat	matrix
times	integer

**Value**

matrix

---

ss_prob	<i>Finds the steady state probabilities from a transition matrix mat =  p_11 p_21 ... p_m1   p_12 p_22 ... p_m2   ... ...   p_1m p_2m ... p_mm  where the columns sum to 1</i>
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**Description**

Finds the steady state probabilities from a transition matrix mat = |p\_11 p\_21 ... p\_m1| |p\_12 p\_22 ... p\_m2| |... ...| |p\_1m p\_2m ... p\_mm| where the columns sum to 1

**Usage**

```
ss_prob(mat)
```

**Arguments**

mat	square SxS matrix of probabilities with column sums of 1. S represents the number of states
-----	---

**Value**

matrix of dimensions Sx1 with steady state probabilities

**Examples**

```
library(kimfilter)
Pm = rbind(c(0.8406, 0.0304),
           c(0.1594, 0.9696))
ss_prob(Pm)
```

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sw_dcf	<i>Stock and Watson Markov Switching Dynamic Common Factor Data Set</i>
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**Description**

Stock and Watson Markov Switching Dynamic Common Factor Data Set

**Usage**

```
data(sw_dcf)
```

**Format**

data.table with columns DATE, VARIABLE, VALUE, and MATURITY The data is monthly frequency with variables ip (industrial production), gmyxpg (total personal income less transfer payments in 1987 dollars), mtq (total manufacturing and trade sales in 1987 dollars), lpnag (employees on non-agricultural payrolls), and dcoinc (the coincident economic indicator)

**Source**

Kim, Chang-Jin and Charles R. Nelson (1999) "State-Space Models with Regime Switching: Classical and Gibbs-Sampling Approaches with Applications" <doi:10.7551/mitpress/6444.001.0001><<http://econ.korea.ac.kr/~cjkim/>>.

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